CGNS/SIDS proposal for extensions – 2008/06/26 – v0.1 – Family RigidMotion 1/1

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Rigid motion applied to a Family for a set of Zones

The proposal is a modification of the $Family_t$ node. The modification re-use existing CGNS structures, but it implies some constraints to $Zone_t$ node and sub-nodes. For time dependent data, this extension is also related with extension 'Modification of BaseIterativeData and ZoneIterativeData for reference frame and family motion'.

First, we propose to allow the <code>RigidGridMotion_t</code> node under the <code>Family_t</code> node. The application of the motion is distributed on each zone having a <code>FamilyName_t</code> FamilyName value corresponding to the <code>Family t</code> node name.

Side-effect:

The use of a set-of-zones structure usually located in the <code>zone_t</code> node raises the issue of Family related data. As a matter of fact, there is no way to indicate in the <code>zone_t</code> time-dependant rigid motion in the case of a Family rigid motion. As the purpose of the Family based rigid motion is to factorize information from a set of Zones, it is not fair to ask the user to indicate the time-dependant motion for each zone.

Remarks:

- 1- It is the responsibility of the user application to find if the Zone has a Family with time iterative data or not. In the case of a time-dependant rigid motion declared at the Family_t level, no *RigidGridMotionPointers* would be found at the Zone_t level.
- 2- The use of a Family rigid motion in at least one Family of a CGNSBase_t implies no Motion node in all Zone t of this CGNSBase t (i.e. no rigid or arbitrary motion).